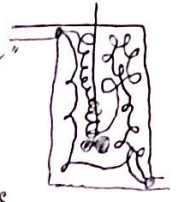


① Segregated flow model

- Basic Assumption and its consequences:
 - "the various fluid elements move through the reactor at different speeds without mixing one another" i.e., they remain segregated
 - we can visualize each fluid element
 - as a batch reactor
 - operating at constant P
 - with holding time equal to the corresponding Residence time for that fluid element.
 - Because there is a distribution of Residence time for various fluid elements, the degree of conversion achieved within each fluid element is different and depends on its Residence time.



Average Conversion at exit stream $\bar{X} = \sum_{\text{all fluid elements}} (\text{fractional conversion for Residence time } t) \times (\text{fraction of fluid elements with Residence time between } t \text{ and } t+\Delta t) \Rightarrow \bar{X} = \sum x(t) \cdot E(t) \cdot \Delta t$

or in integral form $\bar{X} = \int_0^{\infty} x(t) \cdot E(t) dt$

- Hence, to evaluate \bar{X} , the average fractional conversion we need:
 - $x(t)$ → fractional conversion as a function of Residence time from rxn kinetics
 - $E(t)$ → RTD function experimentally measured

- Ex. 01:
 - \bar{X} and $x(t)$ for given kinetics
 - consider a first order liquid phase irreversible rxn: $A \xrightarrow{k_1} B$, $k = 3.33 \times 10^{-3} \text{ s}^{-1}$, $-r_A = kC_A$
 - Estimate the conversion if the rxn is to be carried out in a Non-Ideal reactor for which RTD was measured from the following pulse experiment

- Solution of Ex. 01:
 - we can treat each fluid element as a small batch reactor (CVBR)
 - Design eq. for a CVBR:

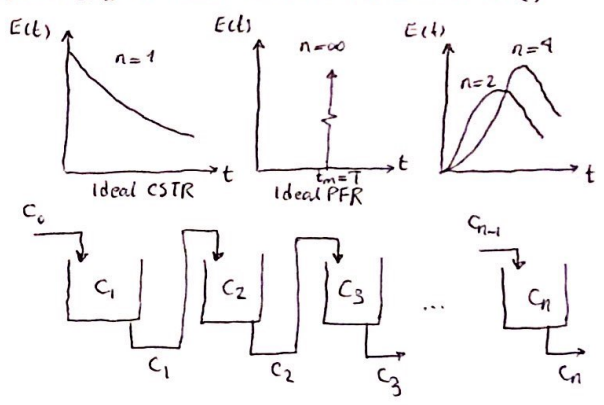
$$-r_A = -\frac{1}{V} \frac{d(C_A V)}{dt} \Rightarrow kC_A = -\frac{dC_A}{dt} \Rightarrow kC_{A_0}(1-x_A) = C_{A_0} \frac{dx_A}{dt} \Rightarrow \frac{dx_A}{1-x_A} = k dt$$
 - integrating $-\ln(1-x_A) \Big|_0^{x_A} = kt \Rightarrow 1-x_A = \exp(-kt) \Rightarrow x_A(t) = 1 - \exp(-kt)$
 - we can estimate $E(t) = \frac{c(t)}{\int_0^{\infty} c(t) dt} = \frac{c(t)}{\sum_0^{\infty} c(t) \cdot \Delta t}$, $\bar{X} = \int_0^{\infty} x(t) \cdot E(t) dt = \sum_0^{\infty} x(t) \cdot E(t) \cdot \Delta t$, $\Delta t = 120 \text{ s}$

time (s)	$c(t)$ (mol/m ³)	$c(t) \cdot \Delta t$ (mol·s/m ³)	$E(t) = \frac{c(t)}{\sum c(t) \cdot \Delta t}$	$x(t) = 1 - \exp(-kt)$	$x(t) \cdot E(t) \cdot \Delta t$
0	0	0	0	0	0
120	6.5	780	1.083×10^{-3}	0.3291	0.0428
240	12.5	1500	2.083×10^{-3}	0.5503	0.1375
360	12.5	1500	2.083×10^{-3}	0.6984	0.1746
480	10.0	1200	1.667×10^{-3}	0.7978	0.1596
600	5.0	600	8.333×10^{-4}	0.8649	0.0864
720	2.5	300	4.167×10^{-4}	0.9091	0.0459
840	1.0	120	1.667×10^{-4}	0.9390	0.0188
960	0	0	0	0.9591	0
1080	0	0	0	0.9726	0
$\sum c(t) \cdot \Delta t = 6000$					
					$\bar{X} = \sum x(t) \cdot E(t) \cdot \Delta t = 0.665$

- Note:
 - we are using RTD function, $E(t)$, directly to obtain the fractional conversion
 - for different rxn kinetics (e.g. reversible, irreversible, series, etc.) the functional form of $x(t)$ would be different

② Tanks in series Model

- Recall that → the performance of n equal size CSTR in series approaches that of a single PFR of the same total V as n → ∞
- Hence → we can in some cases, characterize the observed RTD behavior of a real reactor in terms of n CSTR in series
 - for a real reactor, RTD behavior can fall between two extremes, n=1, and n=∞
 - Objective: given RTD ⇒ get n
 - Now, to develop RTD for CSTR in series



- Let us consider → n equal size CSTR in series
 - liquid phase (constant v for each tank)
 - hence, $\tau_1 = \tau_2 = \tau_3 = \dots = \tau_n$
 - A pulse tracer test, where @ t=0, $C_1 = C_0$
 - General mole balance:

in - out + generation - consumption = accumulation

$$\left. \begin{array}{l}
 1^{st} \text{ tank: } 0 - vC_1 = V_1 \frac{dC_1}{dt} \\
 2^{nd} \text{ tank: } vC_1 - vC_2 = V_2 \frac{dC_2}{dt} \\
 \vdots \\
 n^{th} \text{ tank: } vC_{n-1} - vC_n = V_n \frac{dC_n}{dt}
 \end{array} \right\} \begin{array}{l}
 \text{for constant } v \\
 \text{and equal size} \\
 \text{CSTR: } \tau_i = \frac{V_i}{v} \\
 \tau_i \text{ is for CSTRs}
 \end{array} \left. \begin{array}{l}
 1^{st} \text{ tank: } -C_1 = \tau_1 \frac{dC_1}{dt} \\
 2^{nd} \text{ tank: } C_1 - C_2 = \tau_2 \frac{dC_2}{dt} \\
 \vdots \\
 n^{th} \text{ tank: } C_{n-1} - C_n = \tau_n \frac{dC_n}{dt}
 \end{array}$$

- integrating first eq. using IBC ⇒ $C_1 = C_0 \cdot \exp(-t/\tau_1)$
- for the second eq. ⇒ $C_0 \cdot \exp(-t/\tau_1) - C_2 = \tau_2 \frac{dC_2}{dt} \Rightarrow C_2 = \frac{C_0 t}{\tau_1} \cdot \exp(-t/\tau_1)$
- Similarly: ⇒ $C_n = \frac{C_0 t^{n-1}}{(n-1)\tau_1^{n-1}} \exp(-t/\tau_1)$

$$\int_0^\infty C_n(t) dt = \int_0^\infty \frac{C_0 t^{n-1}}{(n-1)\tau_1^{n-1}} \exp(-t/\tau_1) dt = \frac{C_0}{(n-1)\tau_1^{n-1}} \int_0^\infty t^{n-1} \exp(-t/\tau_1) dt$$

$$= \frac{C_0}{(n-1)\tau_1^{n-1}} (-\tau_1 \exp(-t/\tau_1)) \left[t^{n-1} + (n-1)\tau_1 t^{n-2} + (n-1)(n-2)\tau_1^2 t^{n-3} + \dots + (-1)^{n-1} (n-1)! \tau_1^{n-1} \right]_0^\infty = C_0 \tau_1 (n-2)!$$

$$\bullet E(t) = \frac{C_n(t)}{\int_0^\infty C_n(t) dt} = \frac{\frac{C_0 t^{n-1}}{(n-1)\tau_1^{n-1}} \exp(-t/\tau_1)}{C_0 \tau_1 (n-2)!} \Rightarrow E(t) = \frac{t^{n-1}}{(n-1)! \tau_1^n} \exp(-t/\tau_1)$$

- The important question is that suppose we have measured RTD for a given reactor and we want to model the reactor as n CSTR in series. How can we use RTD measurements to obtain n.

• let $\tau = \frac{V_{total}}{v_0} = \frac{nV_i}{v_0} = n\tau_i \Rightarrow \tau_i = \frac{\tau}{n}$ where $\tau = t_m$ = mean residence time corresponding to the total V

• $E(t) = \frac{t^{n-1}}{(n-1)! (\frac{\tau}{n})^{n-1}} \exp(-\frac{nt}{\tau})$

$$\bullet \sigma^2 = \int_0^\infty (t - t_m)^2 E(t) dt = \int_0^\infty \frac{(t - \tau)^2 t^{n-1} \exp(-\frac{nt}{\tau})}{(n-1)! (\frac{\tau}{n})^n} dt = \frac{1}{(n-1)! (\frac{\tau}{n})^n} \left[\int_0^\infty t^{n+1} \exp(-\frac{nt}{\tau}) dt - 2\tau \int_0^\infty t^n \exp(-\frac{nt}{\tau}) dt + \tau^2 \int_0^\infty t^{n-1} \exp(-\frac{nt}{\tau}) dt \right]$$

$$= \frac{1}{(n-1)! (\frac{\tau}{n})^n} \left[(n+1)! (\frac{\tau}{n})^{n+2} - 2\tau (\frac{\tau}{n})^{n+1} + \tau^2 (\frac{\tau}{n})^n \cdot (n-1)! \right] = n(n+1) (\frac{\tau}{n})^2 - 2\tau (\frac{\tau}{n}) + \tau^2$$

$$= (\frac{n+1}{n}) \tau^2 - 2\tau^2 + \tau^2 = \tau^2 (\frac{n+1}{n} - 1) = \tau^2 (\frac{n+1-n}{n}) \Rightarrow \sigma^2 = \frac{\tau^2}{n} \quad \text{or} \quad n = \frac{\tau^2}{\sigma^2}$$

- If we want to model a reactor as n-tanks in series → we can assume $\left. \begin{array}{l} t_m = \tau \\ \sigma^2 \end{array} \right\} \Rightarrow n = \frac{t_m^2}{\sigma^2}$

- Recall that for n CSTR in series (each, of equal V), for 1st order, irreversible, liquid phase rxn we have:

$$\frac{C_{A0} - C_{A1}}{\tau_1} = kC_{A1}, \quad \frac{C_{A1} - C_{A2}}{\tau_2} = kC_{A2}, \quad \frac{C_{A2} - C_{A3}}{\tau_3} = kC_{A3}, \quad \dots, \quad \frac{C_{A_{n-1}} - C_{An}}{\tau_n} = kC_{An}$$

$$\frac{C_{A1}}{C_{A0}} = \frac{1}{1+k\tau_1}, \quad \frac{C_{A2}}{C_{A1}} = \frac{1}{1+k\tau_2}, \quad \frac{C_{A3}}{C_{A2}} = \frac{1}{1+k\tau_3}, \quad \dots, \quad \frac{C_{An}}{C_{A_{n-1}}} = \frac{1}{1+k\tau_n}$$

• if $\tau_1 = \tau_2 = \tau_3 = \dots = \tau_n = \frac{\tau}{n}$ then $\frac{C_{An}}{C_{A0}} = \frac{1}{(1+k\frac{\tau}{n})^n}$

• $x_{An} = \frac{C_{A0} - C_{An}}{C_{A0}} = 1 - \frac{C_{An}}{C_{A0}} \Rightarrow x_{An} = 1 - \frac{1}{(1+k\frac{\tau}{n})^n}$

- Ex. 02 \rightarrow Liquid phase reactor, 1st order rxn, $k = 0.1 \text{ min}^{-1}$, $t_m = 10 \text{ min}$, $\sigma^2 = 24 \text{ min}^2$

$$n = \frac{t_m^2}{\sigma^2} = \frac{10^2}{24} = 4.167, \quad x_A = 1 - \frac{1}{(1+0.1 \frac{10}{4.167})^{4.167}} \Rightarrow x_A = 0.592$$

- for other rate functions \rightarrow e.g. 2nd order, reversible, etc.
 \rightarrow we need to evaluate conversion at the exit of each reactor sequentially
 \rightarrow In the above case, find conversion for $n=4$, and 5, and interpolate

③ Axial Dispersion Model

- Assumptions \rightarrow Plug flow with some degree of back mixing

\rightarrow Deviation from plug flow is taken into account by an effective axial diffusivity, D_L

- MBE \rightarrow for a non-reacting tracer injected into the reactor ($C \triangleq$ concentration of tracer)

$$(F_{in} - F_{out}) \Delta t = (C \Delta V) \Big|_{t+\Delta t} - (C \Delta V) \Big|_t$$

\rightarrow assuming constant volumetric flowrate $\dot{v} = u A_{\phi}$

$$F_{in} = \dot{v} C \Big|_z + (-A_{\phi} D_L \frac{\partial C}{\partial z}) \Big|_z, \quad \text{and similarly } F_{out} = \dot{v} C \Big|_{z+\Delta z} + (-A_{\phi} D_L \frac{\partial C}{\partial z}) \Big|_{z+\Delta z}$$

\rightarrow Substituting in the MBE and taking the limit as $\Delta z \rightarrow 0$, we obtain: $\frac{\partial C}{\partial t} = D_L \frac{\partial^2 C}{\partial z^2} - u \frac{\partial C}{\partial z}$ (1)

\rightarrow In dimensionless form $\theta = \frac{t}{t_m} = \frac{tu}{L}$, $x = \frac{uz + z}{L}$

\rightarrow eq. 1 becomes: $\frac{\partial C}{\partial \theta} = \left(\frac{D_L}{uL} \right) \frac{\partial^2 C}{\partial x^2} - \frac{\partial C}{\partial x}$ (2)

\rightarrow $\frac{D_L}{uL}$ is called "Vessel dispersion No." which measures the extent of axial dispersion

\rightarrow $\frac{D_L}{uL} \rightarrow 0 \equiv$ negligible dispersion, plug flow

\rightarrow $\frac{D_L}{uL} \rightarrow \infty \equiv$ large dispersion, CSTR

- Considering eq. 1 with a step input of tracer, C_0

\rightarrow boundary conditions are $C = C_0$ @ $z = -\infty$, for $t \geq 0$

$\rightarrow C = 0$ @ $z = +\infty$, for $t \geq 0$

$\rightarrow C = 0$ @ $z > 0$, for $t = 0$

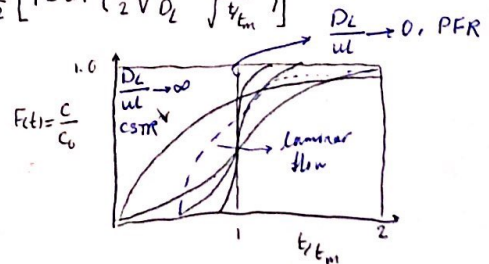
$\rightarrow C = 0$ @ $z < 0$, for $t = 0$

\rightarrow solution procedure usually numerical

\rightarrow but for small values of $\frac{D_L}{uL}$, an approximate analytical is as follows:

$$\left(\frac{C}{C_0} \right)_{\text{step}} = \frac{1}{2} \left[1 - \text{erf} \left(\frac{1}{2} \sqrt{\frac{uL}{D_L}} \cdot \frac{1-t/t_m}{\sqrt{t/t_m}} \right) \right]$$

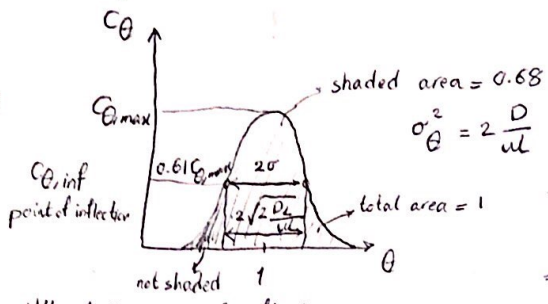
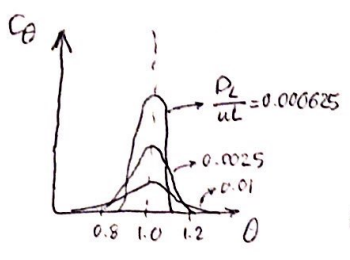
\rightarrow The dispersion model presupposes that the mixing state can be represented by a particular value of $\frac{D_L}{uL}$ (one that best fits the measured RTD)



- For small values of $\frac{D_L}{uL}$, an approximate analytical solution for eq. 1, for a pulse input of C_0 is given by:

$$t_m \left(\frac{C}{C_0} \right)_{\text{pulse}} = C_\theta = \frac{1}{2\sqrt{\pi \frac{D_L}{uL}}} \exp\left(-\frac{(1-t/t_m)^2}{4 \frac{D_L}{uL}}\right) \text{ which gives symmetrical } C_\theta \text{ curve}$$

- dimensionless units: $\theta = \frac{t}{t_m}$, $C_\theta = t_m C$, $C = \frac{c(t)}{C_0}$, $E_\theta = t_m E$, $\theta_m = 1$, $F_B = F$, $\sigma_\theta^2 = \frac{\sigma^2}{t_m^2}$



$$\sigma_\theta^2 = 2 \frac{D}{uL}, \sigma_\theta = \frac{\sigma}{t_m}$$

$$t_m = \frac{L}{u}$$

$$\Rightarrow \sigma^2 = 2 \left(\frac{DL}{u^3} \right) \text{ (variance of } c \text{ curve)}$$

- $\frac{D_L}{uL}$ can be obtained from: variance, max height, width at the point of inflection

- For series of vessels

- means and variances are additive
- $\sigma_{\text{overall}}^2 = \sigma_{\text{vessel a}}^2 + \sigma_{\text{vessel b}}^2$
- $t_{m, \text{overall}} = t_{m, \text{vessel a}} + t_{m, \text{vessel b}}$

- The treatment presented so far was for small extent of dispersion, where an approximate analytical solution was used.

→ Comparison with more complex but exact solutions indicate:

error < 5% for $\frac{D}{uL} < 0.01$

error < 0.5% for $\frac{D}{uL} < 0.001$

→ furthermore, this treatment is valid for both open and closed vessel

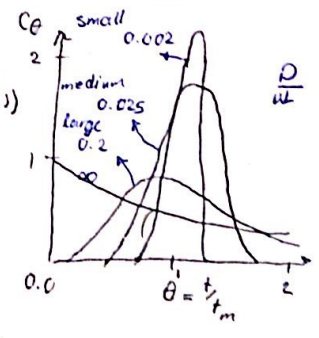
• closed vessel → Inlet and Outlet to vessel are plug flow

• open vessel → " " " also have the same D as the vessel.

- For large extent of Dispersion

→ closed vessel + pulse input

- $\bar{C}_c = 1$
- $\sigma_\theta^2 = 2 \frac{D}{uL} - 2 \left(\frac{D}{uL} \right)^2 \cdot (1 - \exp(-\frac{uL}{D}))$
- C_θ is obtained numerically



→ Open vessel

Analytical solution:

- $C_\theta = \frac{1}{2\sqrt{10 \left(\frac{D}{uL} \right)}} \exp\left[-\frac{(1-\theta)^2}{4 \left(\frac{D}{uL} \right)}\right]$
- $\bar{C}_c = 1 + 2 \frac{D}{uL}$
- $\sigma_\theta^2 = 2 \frac{D}{uL} + 8 \left(\frac{D}{uL} \right)^2$

- See examples 3-5 from text. for calculation of $\frac{D}{uL}$ from RTD