



Computational Fluid Dynamics (CFD)

Introductory Course

Session 01 – Basic Concepts of CFD

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Syllabus :

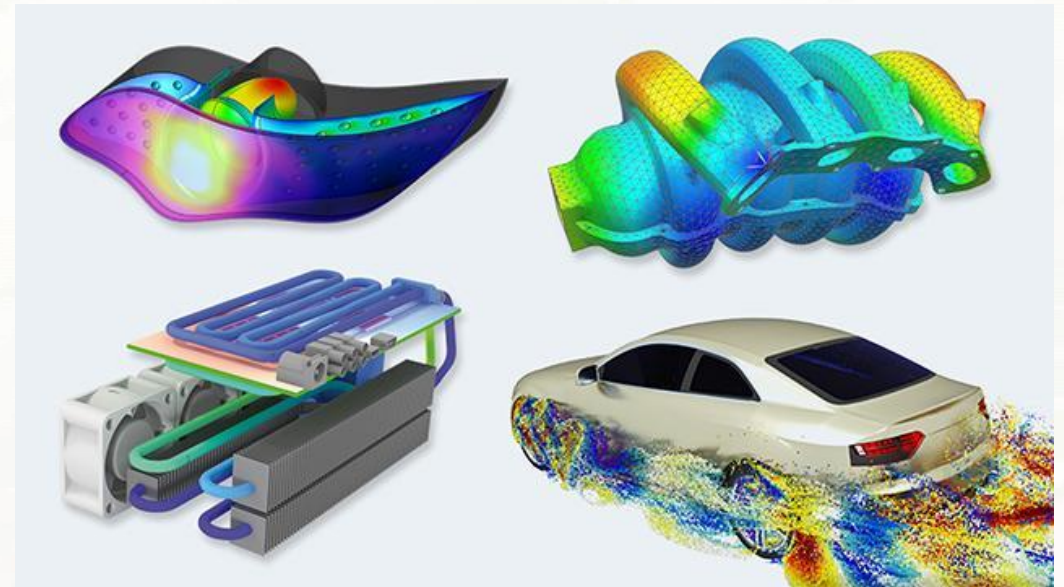
- Session 01 – Basic Concepts of CFD
- Session 02 – Review of Vector Calculus
- Session 03 – Introduction to Numerical Methods
- Session 04 – Mathematical Description of Physical Phenomena – Part 01
- Session 05 – Mathematical Description of Physical Phenomena – Part 02



1. What is CFD ?

- **Definition.** A branch of Fluid Mechanics that uses numerical methods and algorithms to solve and analyze problems that involves fluid flows

- Governing equations of fluid mechanics include :
 - Continuity eq.
 - Momentum eq.
 - Energy eq.





2. Introduction to CFD

□ Typical steps of a the CFD Process :

Problem Definition

Mesh Generation

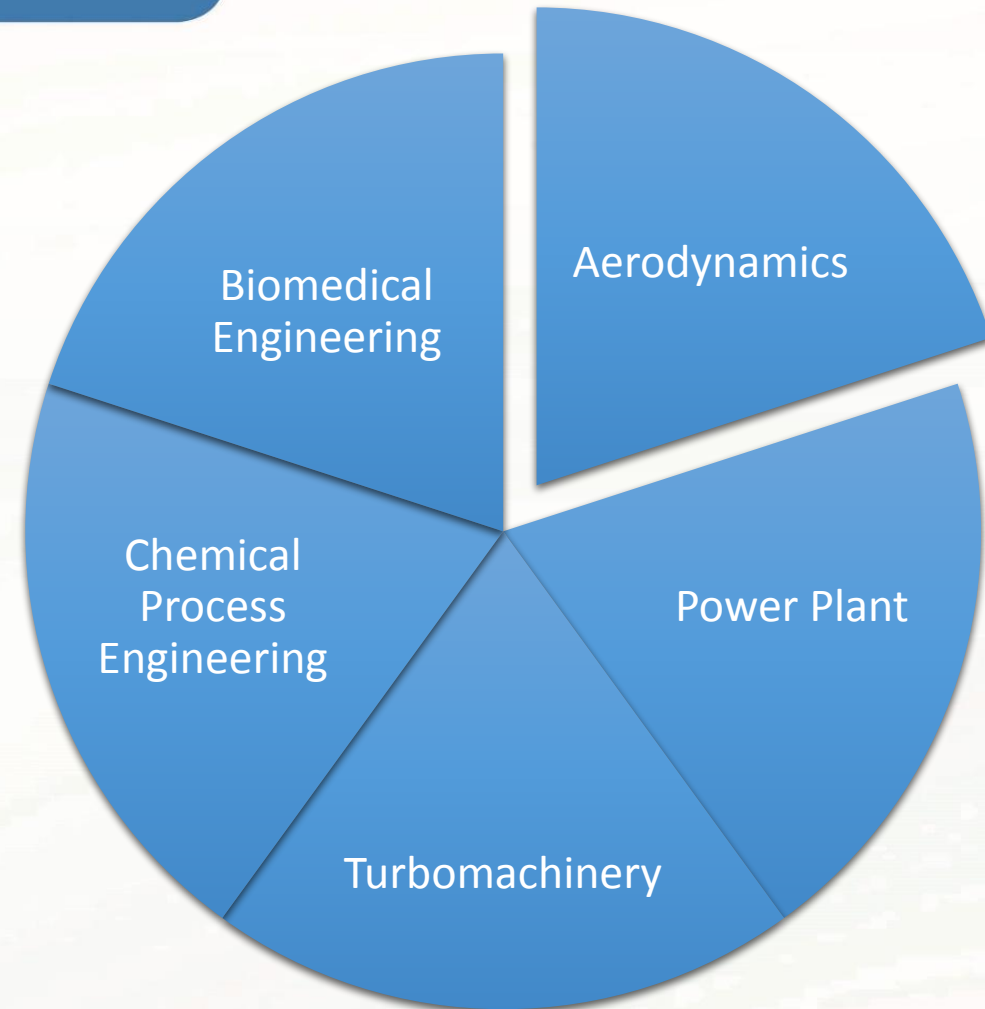
Solver Setup

Solution

Post-Processing



3. Applications of CFD





4. Adv. Vs. Disadv. of CFD

Advantages

- Cost-Effective
- Flexibility
- Accuracy
- Visualization
- Optimization

Limitations

- Boundary Conditions
- Numerical Errors
- Complexity
- Validation
- Assumptions



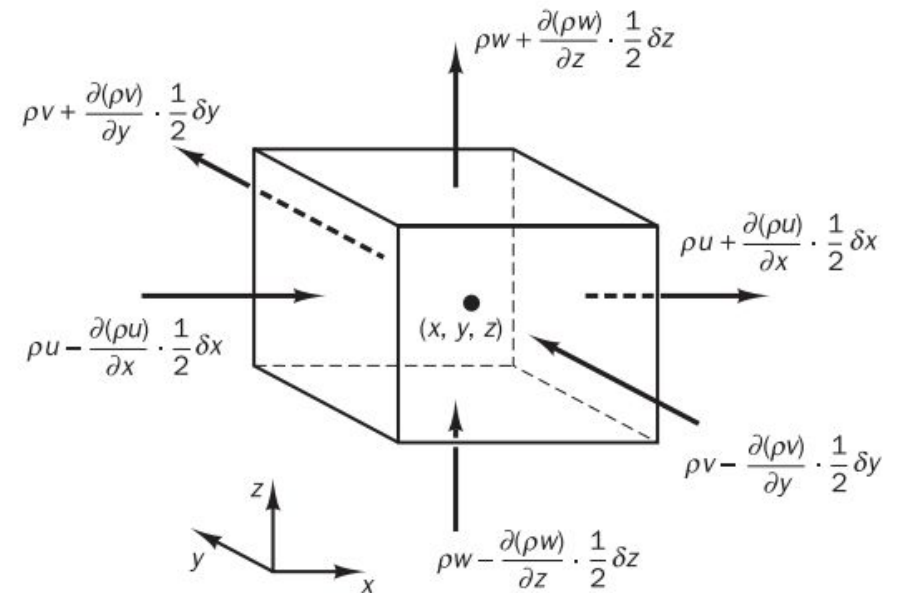
5. Governing eqs.

□ Continuity Eq. (Mass Conservation Law)

- The General case.
- Simple forms
 - Incompressible fluid
 - Steady State flow

$$\frac{\partial \rho}{\partial t} + \text{div}(\rho \mathbf{u}) = 0$$

Rate of increase of mass in fluid element	=	Net rate of flow of mass into fluid element
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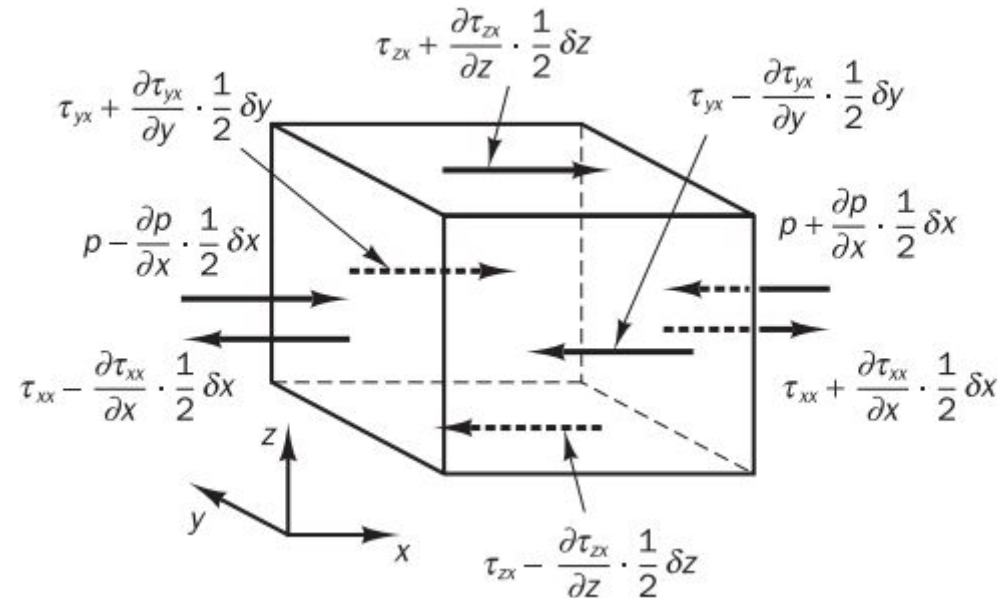


5. Governing eqs.

□ Momentum Eq. (Linear Momentum Conservation Law)

- The General case.
- **surface forces**
 - pressure forces
 - viscous forces
 - gravity force
- **body forces**
 - centrifugal force
 - Coriolis force
 - electromagnetic force

Rate of increase of momentum of fluid particle	=	Sum of forces on fluid particle
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$$\frac{\partial}{\partial t} [\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = -\nabla p + \mu \nabla^2 \mathbf{v} + \mathbf{f}_b$$



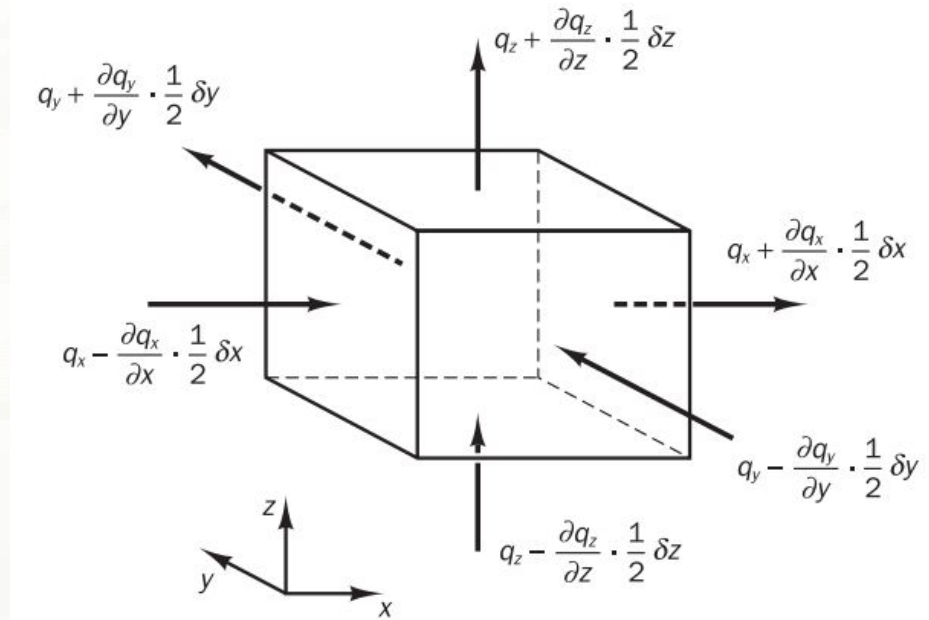
5. Governing eqs.

□ Energy Eq. (Energy Conservation Law)

- The General case.

$$\frac{\partial}{\partial t} (\rho c_p T) + \nabla \cdot [\rho c_p \mathbf{v} T] = \nabla \cdot [k \nabla T] + Q^T$$

Rate of increase of energy of fluid particle	=	Net rate of heat added to fluid particle	+	Net rate of work done on fluid particle
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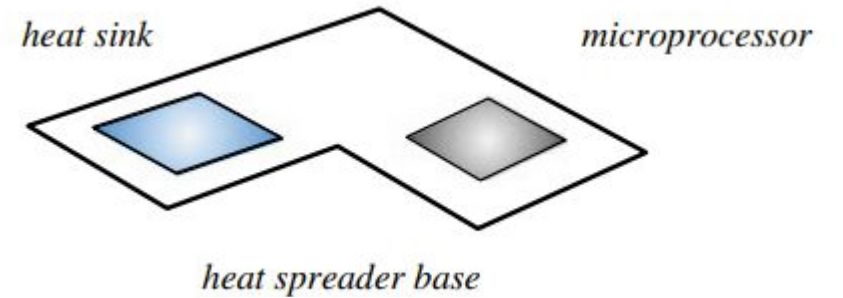
6. Numerical Methods

- Finite Difference Methods
 - Discretizes the domain into a grid
- Finite Element Methods
 - Discretizes the domain into small element
- Finite Volume Methods
 - Discretizes the domain into small control volumes
- Spectral Methods
 - Based on approximation of the solution of the PDE using a basis function
- Boundary Element Methods
 - Puts a focus on exterior region of the physical domain
- Galerkin Methods
 - Forefather of FEM
- Lattice-Boltzmann Methods

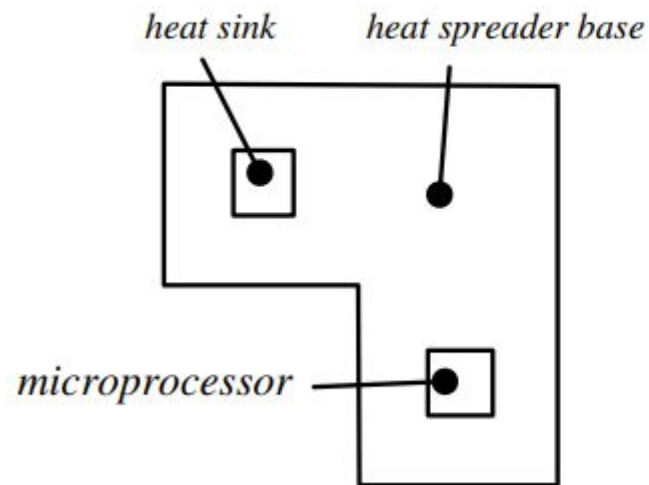


7. Steps to solving

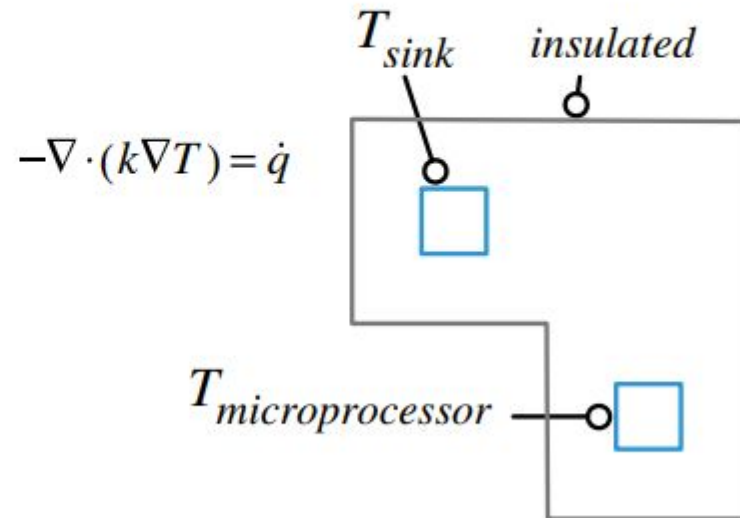
- Step 1. “ Geometric and Physical Modeling “



✓ Domain Modeling



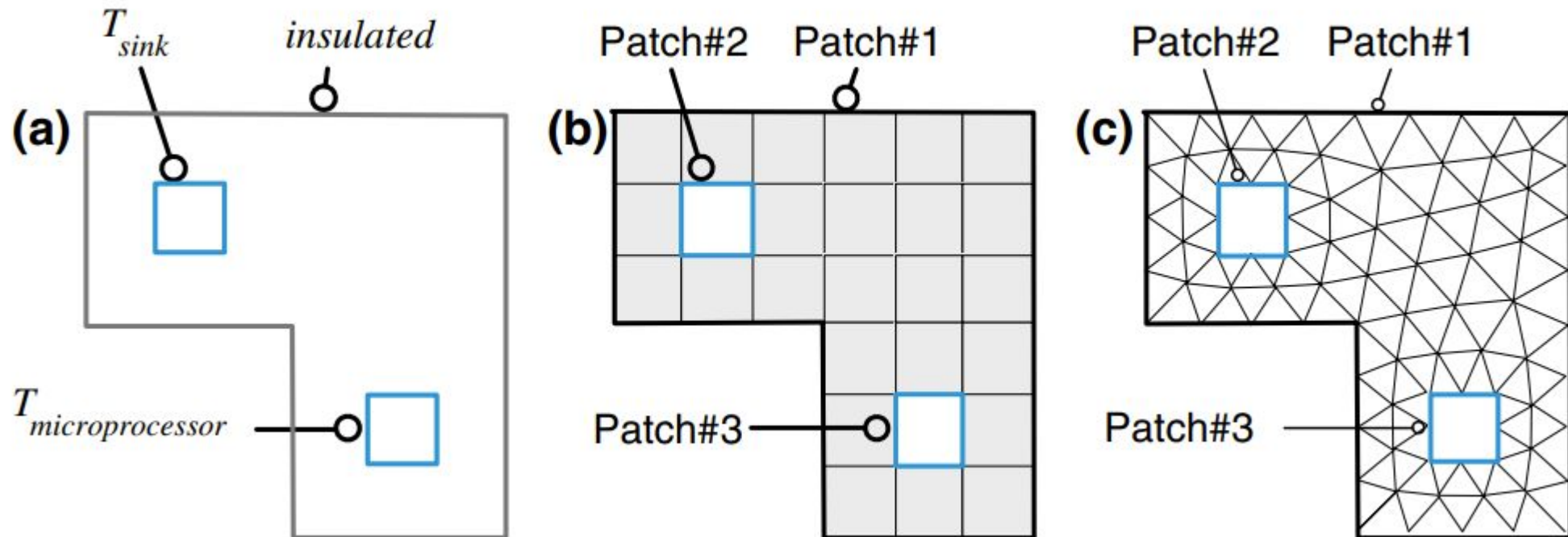
✓ Physical Modeling





7. Steps to solving

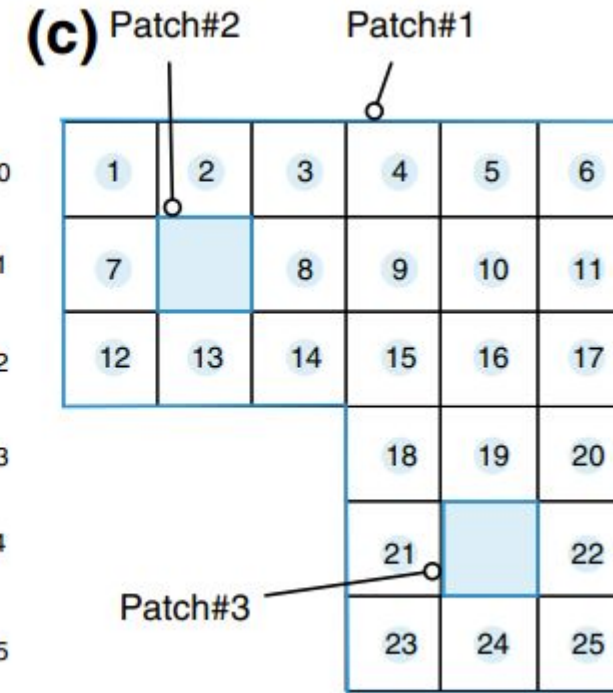
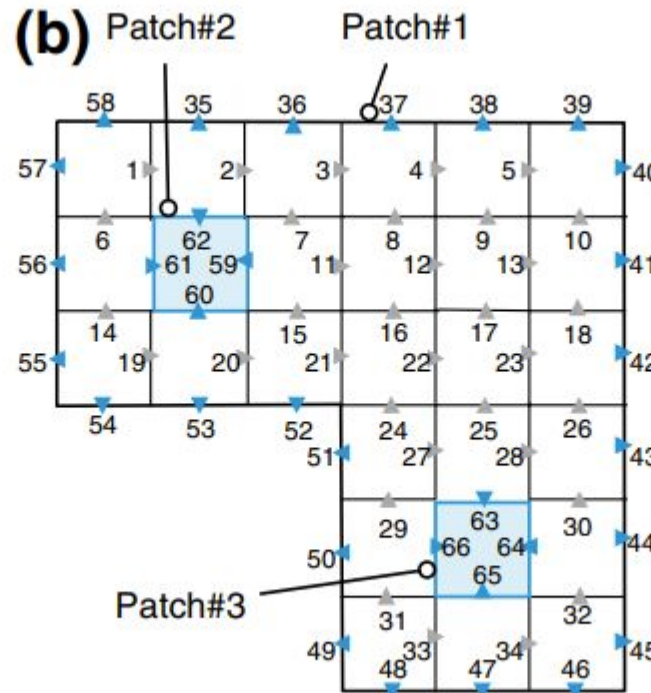
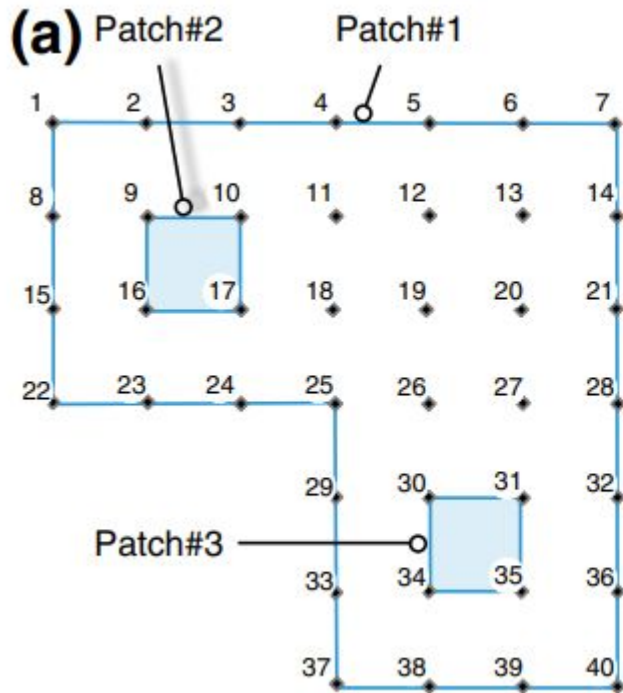
- Step 2. “ Domain Discretization (Mesh Generation) “





7. Steps to solving

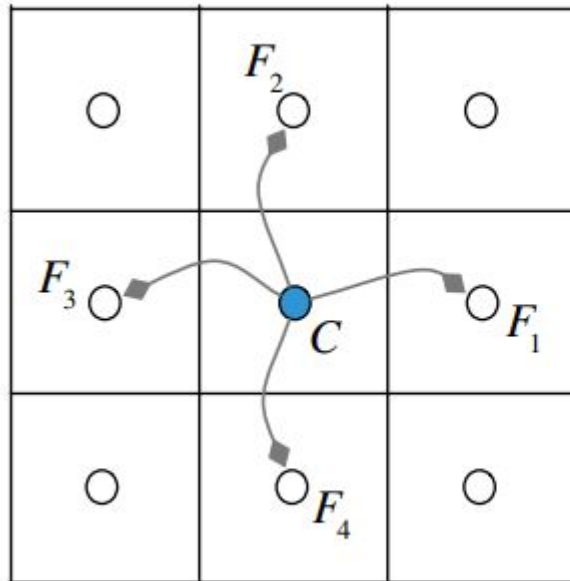
- Step 2. “ Domain Discretization (Mesh Generation) ” – Mesh Topology





7. Steps to solving

- Step 2. “ Domain Discretization (Mesh Generation) ” – Element Connectivity



Element 9 Connectivity

Neighbours [10 4 8 15]

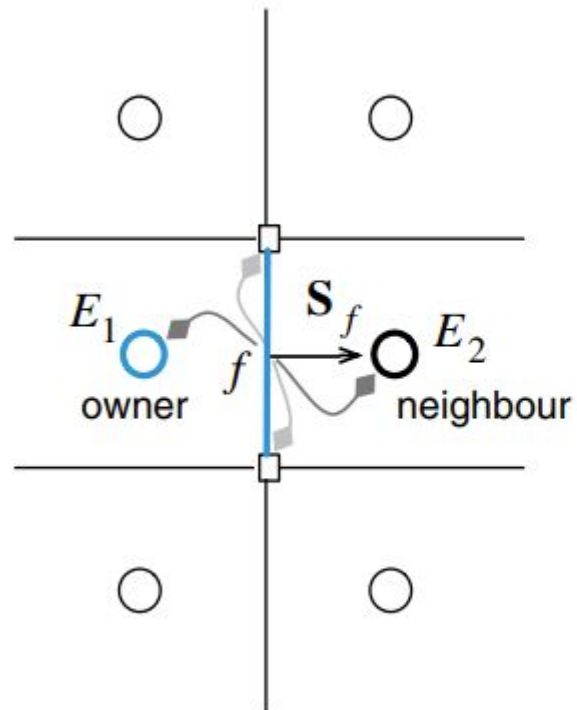
Faces [12 8 11 16]

Vertices [19 11 12 18]



7. Steps to solving

- Step 2. “ Domain Discretization (Mesh Generation) ” – Face Connectivity



Face 12 Connectivity

Element1 9

Element2 10

Vertices [19 12]



7. Steps to solving

- Step 3. “ Equation Discretization (Numerical Approximation) “

$$-\sum_{f \sim nb(C)} (k \nabla T)_f \cdot \mathbf{S}_f = \dot{q}_c V_C$$

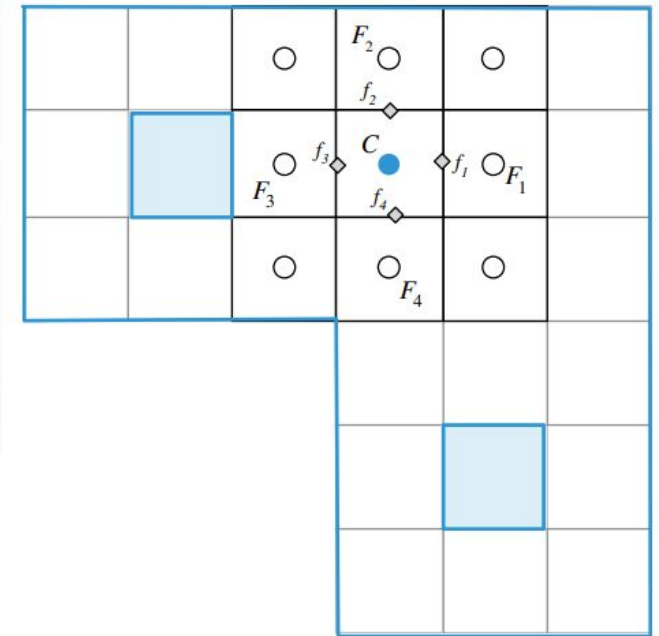
$$-(k \nabla T)_{f_1} \cdot \mathbf{S}_{f_1} - (k \nabla T)_{f_2} \cdot \mathbf{S}_{f_2} - (k \nabla T)_{f_3} \cdot \mathbf{S}_{f_3} - (k \nabla T)_{f_4} \cdot \mathbf{S}_{f_4} = \dot{q}_c V_C$$

$$\mathbf{S}_{f_1} = \Delta y_{f_1} \mathbf{i}$$

$$\delta x_{f_1} = x_{F_1} - x_C$$

$$\nabla T_{f_1} = \left(\frac{\partial T}{\partial x} \right)_{f_1} \mathbf{i} + \left(\frac{\partial T}{\partial y} \right)_{f_1} \mathbf{j}$$

$$\nabla T_{f_1} \cdot \mathbf{S}_{f_1} = \frac{T_{F_1} - T_C}{\delta x_{f_1}} \Delta y_{f_1}$$



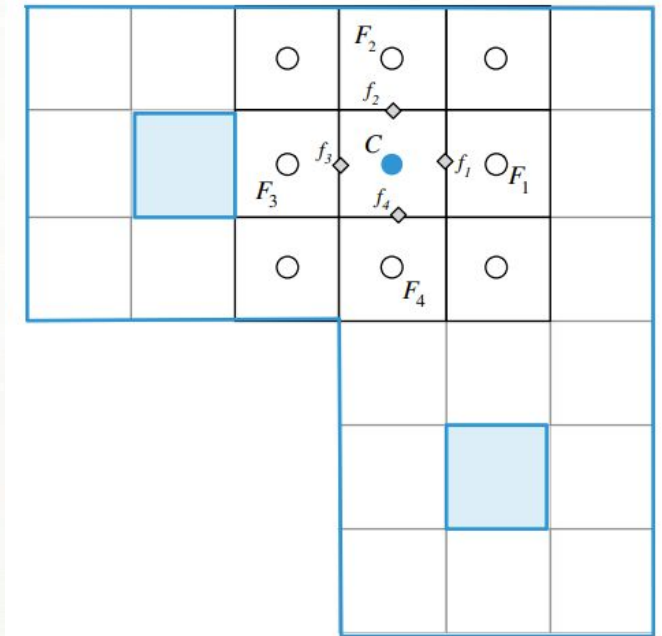


7. Steps to solving

- Step 3. “ Equation Discretization (Numerical Approximation) “

$$-(k\nabla T)_{f_1} \cdot \mathbf{S}_{f_1} = a_{F_1}(T_{F_1} - T_C) \quad a_{F_1} = -k \frac{\Delta y_{f_1}}{\delta x_{f_1}}$$

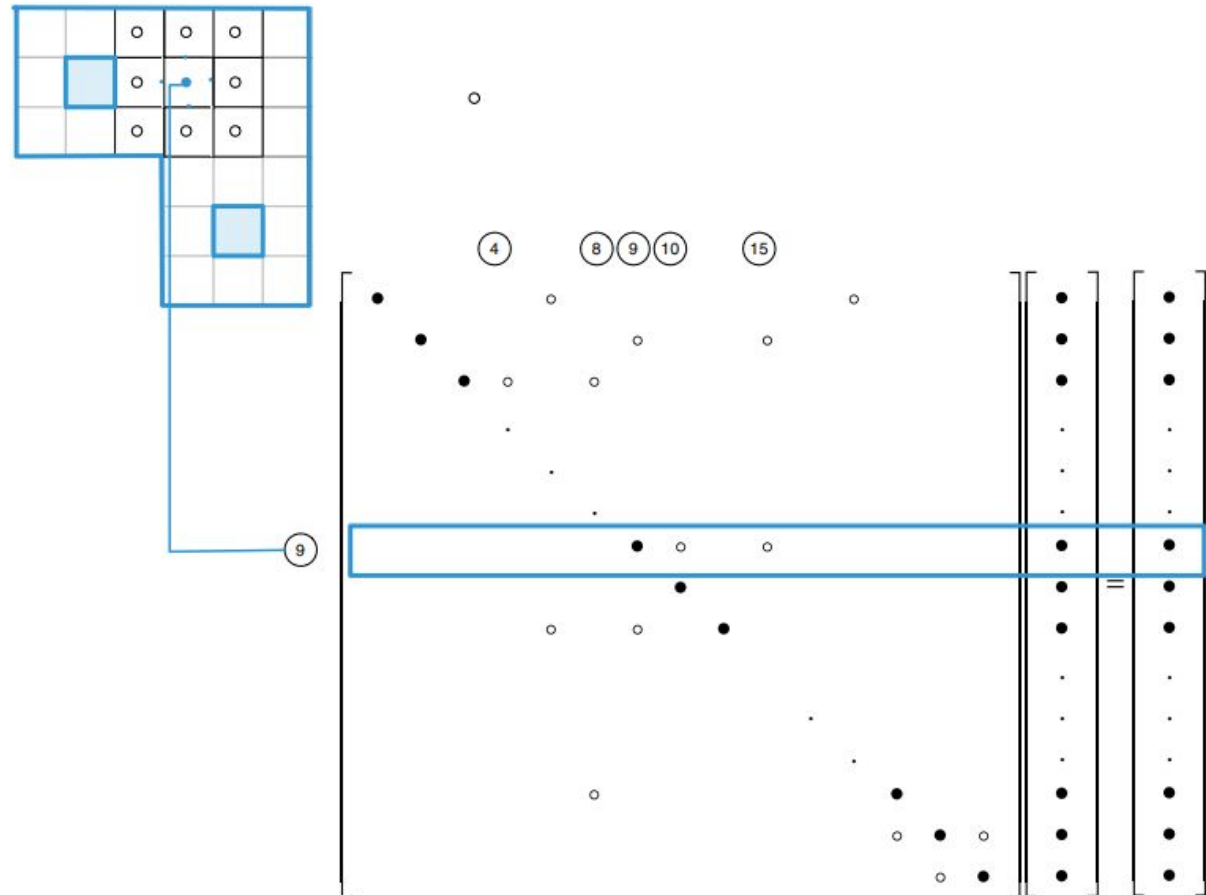
$$\begin{aligned} - \sum_{f \sim nb(C)} (k\nabla T)_f \cdot \mathbf{S}_f &= \sum_{F \sim NB(C)} a_F(T_F - T_C) \\ &= -(a_{F_1} + a_{F_2} + a_{F_3} + a_{F_4})T_C + a_{F_1}T_{F_1} + a_{F_2}T_{F_2} + a_{F_3}T_{F_3} + a_{F_4}T_{F_4} \\ &= \dot{q}_C V_C \end{aligned}$$





7. Steps to solving

- Step 3. “ Equation Discretization (Numerical Approximation) “





7. Steps to solving

□ Step 4. “ Solution of the Discretized Equation “

□ Direct Methods

□ Iterative Methods

$$\mathbf{A}[T] = \mathbf{b}$$

$$[T] = \mathbf{A}^{-1}\mathbf{b}$$

$$T_C = \frac{-\sum_{F \sim NB(C)} a_F T_F + b_C}{a_C}$$



8. Importance of Mathematics

- Partial Differential Equations (PDEs)

$$[\rho D\mathbf{v}/Dt = -\nabla p + \mu \nabla^2 \mathbf{v} + \rho \mathbf{g}]$$

Cartesian coordinates (x, y, z):

$$\rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = -\frac{\partial p}{\partial x} + \mu \left[\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right] + \rho g_x \quad (\text{B.6-1})$$

$$\rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = -\frac{\partial p}{\partial y} + \mu \left[\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right] + \rho g_y \quad (\text{B.6-2})$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial p}{\partial z} + \mu \left[\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right] + \rho g_z \quad (\text{B.6-3})$$



Thanks for your
time and attention