

### Computational Fluid Dynamics (CFD)

### Introductory Course

#### Session 03 – Introduction to Numerical Methods

Lecturer: Amirhossein Alivandi March 2023



## Syllabus :

- Session 01 Basic Concepts of CFD
- Session 02 Review of Vector Calculus
- Session 03 Mathematical Description of Physical Phenomena



#### 1. Properties of Numerical Solution Methods

ConsistencyTruncation Error

#### □ Stability

- □ For Steady Problems
- □ For Temporal Problems
- □ For Numerical Methods
- □ Convergence
- □ Conservation
- Boundedness



#### 2. Eulerian and Lagrangian Description of Conservation Laws

Lagrangian. Follows the particles of fluid as they move through space and time
 Eulerian. Focuses on specific locations in the flow region as time passes





3. Substantial vs. Local Derivative

- **a** Rate of change of a variable  $\phi(t, \mathbf{x}(t))$ .
- $\Box$  Eulerian (local) Derivative  $(\partial \phi / \partial t)$
- $\square$  Lagrangian (substantial)  $(D\phi/Dt)$





3. Substantial vs. Local Derivative

**\Box** Rate of change of a variable  $\phi(t, \mathbf{x}(t))$ .

 $\Box$  Eulerian (local) Derivative  $(\partial \phi / \partial t)$ 

 $\square$  Lagrangian (substantial)  $(D\phi/Dt)$ 

$$\frac{D\mathbf{v}}{Dt} = \frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla)\mathbf{v}$$





4. Reynolds Transport Theorem

- □ Is used to express the conservation laws to an Eulerian Approach (Control Volumes)
- Let **B** be any property of the fluid (mass, momentum, energy, etc.)
- $\square$  Thus, intensive value of B will be b=dB/dm
- □ The instantaneous change of B in MV

$$\left(\frac{dB}{dt}\right)_{MV} = \frac{d}{dt} \left(\int_{V(t)} b\rho dV\right) + \int_{S(t)} b\rho \mathbf{v}_r \cdot \mathbf{n} \, dS$$

$$\mathbf{v}_r = \mathbf{v}(t, \mathbf{X}) - \mathbf{v}_s(t, \mathbf{X})$$



4. Reynolds Transport Theorem

 $\square$  For a fixed CV,  $\mathbf{v}_s = \mathbf{0}$  , thus using Leibniz rule:

$$\left(\frac{dB}{dt}\right)_{MV} = \int_{V} \frac{\partial}{\partial t} (b\rho) dV + \int_{S} b\rho \mathbf{v} \cdot \mathbf{n} \, dS$$

$$\frac{d}{dt}\left(\int\limits_{V} b\rho \ dV\right) = \int\limits_{V} \frac{\partial}{\partial t} (b\rho) dV$$

Using Divergence Theorem:

$$\left(\frac{dB}{dt}\right)_{MV} = \int_{V} \left[\frac{\partial}{\partial t}(\rho b) + \nabla \cdot (\rho \mathbf{v} b)\right] dV$$

$$\left(\frac{dB}{dt}\right)_{MV} = \int_{V} \left[\frac{D}{Dt}(\rho b) + \rho b\nabla \cdot \mathbf{v}\right] dV$$

1



#### 5. Conservation of Mass Continuity eq.

- □ What is says
- □ Using Lagrangian approach:

$$\left(\frac{dm}{dt}\right)_{MV} = 0$$

Defining :

$$B = m$$
$$b = 1$$





5. Conservation of Mass Continuity eq.

Using Reynolds Transport Theorem

For any CV : 

□ Special Cases

 $\int_{U} \left( \frac{\partial \rho}{\partial t} + \nabla \cdot \left[ \rho \mathbf{v} \right] \right) dV = 0$ 

 $\frac{\partial \rho}{\partial t} + \nabla \cdot \left[ \rho \mathbf{v} \right] = 0$ 

 $\nabla \cdot \mathbf{v} = 0$ 



6. Conservation of Linear Momentum

□ What it says

Using Lagrangian approach:

$$\left(\frac{d(m\mathbf{v})}{dt}\right)_{MV} = \left(\int_{V} \mathbf{f} \, dV\right)_{MV}$$

□ For the moving fluid:

$$\left(\int\limits_{V} \mathbf{f} \, dV\right)_{MV} = \int\limits_{V} \mathbf{f} \, dV$$





6. Conservation of Linear Momentum

 $\square$  Using the Reynolds Transport Theorem with  $b = \mathbf{v}$ ,

$$\int_{V} \left[ \frac{\partial}{\partial t} [\rho \mathbf{v}] + \nabla \cdot \{ \rho \mathbf{v} \mathbf{v} \} - \mathbf{f} \right] dV = 0$$

□ For any CV :

$$\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = \mathbf{f}$$

 $\rho \mathbf{v} \mathbf{v}$  is the dyadic product.

$$\mathbf{f} = \mathbf{f}_s + \mathbf{f}_b$$



6. Conservation of Linear Momentum Surface Forces

□ The Stress Tensors

$$\Sigma = egin{pmatrix} \Sigma_{xx} & \Sigma_{xy} & \Sigma_{xz} \ \Sigma_{yx} & \Sigma_{yy} & \Sigma_{yz} \ \Sigma_{zx} & \Sigma_{zy} & \Sigma_{zz} \end{pmatrix}$$

□ In Practice:

$$\Sigma = -\begin{pmatrix} p & 0 & 0 \\ 0 & p & 0 \\ 0 & 0 & p \end{pmatrix} + \begin{pmatrix} \overbrace{\mathbf{x}_{xx}}^{\tau_{xx}} & \tau_{xy} & \tau_{xz} \\ \overbrace{\mathbf{x}_{yx}}^{\tau_{yy}} & \overbrace{\mathbf{x}_{yy}}^{\tau_{yz}} & \tau_{yz} \\ \tau_{yx} & \overbrace{\mathbf{x}_{yy}}^{\tau_{zz}} & \overbrace{\mathbf{x}_{zz}+p}^{\tau_{zz}} \end{pmatrix} = -p\mathbf{I} + \mathbf{\tau}$$

 $\mathbf{f}_s = \boldsymbol{\Sigma} \cdot d\mathbf{S} = \boldsymbol{\Sigma} \cdot \mathbf{n} dS$ 

n



6. Conservation of Linear Momentum Surface Forces

Due to the illustration and by applying the divergence theorem:

$$\int_{V} \mathbf{f}_{s} \, dV = \int_{S} \mathbf{\Sigma} \cdot \mathbf{n} \, dS = \int_{V} \nabla \cdot \mathbf{\Sigma} \, dV$$

Thus:

$$\mathbf{f}_s = [\nabla \cdot \boldsymbol{\Sigma}] = -\nabla p + [\nabla \cdot \boldsymbol{\tau}]$$





6. Conservation of Linear Momentum Body Forces – Gravitational

□ Gravitational Force







6. Conservation of Linear Momentum Body Forces – System Rotation

□ In a rigid rotating body

$$\mathbf{f}_{b} = \underbrace{-2\rho[\boldsymbol{\varpi} \times \mathbf{v}]}_{Coriolis\,forces} - \underbrace{\rho[\boldsymbol{\varpi} \times [\boldsymbol{\varpi} \times \mathbf{r}]]}_{Centrifugal\,forces}$$





6. Conservation of Linear Momentum General form

 Without Considering body forces, electric, and magnetic forces, we've come to :

# $\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = -\nabla p + [\nabla \cdot \tau] + \mathbf{f}_b$



- 6. Conservation of Linear Momentum General form – for Newtonian Fluids
- □ Stress Tensor for a Newtonian Fluid:

$$\mathbf{\tau} = \mu \Big\{ \nabla \mathbf{v} + (\nabla \mathbf{v})^{\mathrm{T}} \Big\} + \lambda (\nabla \cdot \mathbf{v}) \mathbf{I}$$

$$\boldsymbol{\tau} = \begin{bmatrix} 2\mu \frac{\partial u}{\partial x} + \lambda \nabla \cdot \mathbf{v} & \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) & \mu \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \\ \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) & 2\mu \frac{\partial v}{\partial y} + \lambda \nabla \cdot \mathbf{v} & \mu \left( \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right) \\ \mu \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) & \mu \left( \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right) & 2\mu \frac{\partial w}{\partial z} + \lambda \nabla \cdot \mathbf{v} \end{bmatrix}$$

□ Thus,



- 6. Conservation of Linear Momentum General form – for Newtonian Fluids
- $\hfill\square$  We need the divergence of the stress tensor

$$\begin{split} \left[ \nabla \cdot \mathbf{\tau} \right] &= \nabla \cdot \left[ \mu \left( \nabla \mathbf{v} + (\nabla \mathbf{v})^{\mathrm{T}} \right) \right] + \nabla (\lambda \nabla \cdot \mathbf{v}) \\ &= \begin{bmatrix} \frac{\partial}{\partial x} \left[ 2\mu \frac{\partial u}{\partial x} + \lambda \nabla \cdot \mathbf{v} \right] + \frac{\partial}{\partial y} \left[ \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \frac{\partial}{\partial z} \left[ \mu \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \right] \\ &= \begin{bmatrix} \frac{\partial}{\partial x} \left[ \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \frac{\partial}{\partial y} \left[ 2\mu \frac{\partial v}{\partial y} + \lambda \nabla \cdot \mathbf{v} \right] + \frac{\partial}{\partial z} \left[ \mu \left( \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right) \right] \\ &= \begin{bmatrix} \frac{\partial}{\partial x} \left[ \mu \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \right] + \frac{\partial}{\partial y} \left[ 2\mu \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right] + \frac{\partial}{\partial z} \left[ 2\mu \frac{\partial w}{\partial z} + \lambda \nabla \cdot \mathbf{v} \right] \end{bmatrix} \end{split}$$



- 6. Conservation of Linear Momentum General form – for Newtonian Fluids
- □ In the closed form

$$\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = -\nabla p + \nabla \cdot \left\{ \mu \left[ \nabla \mathbf{v} + (\nabla \mathbf{v})^{\mathrm{T}} \right] \right\} + \nabla (\lambda \nabla \cdot \mathbf{v}) + \mathbf{f}_{b}$$

$$\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = \nabla \cdot \{\mu \nabla \mathbf{v}\} - \nabla p + \underbrace{\nabla \cdot \left\{\mu (\nabla \mathbf{v})^{\mathrm{T}}\right\} + \nabla (\lambda \nabla \cdot \mathbf{v}) + \mathbf{f}_{b}}_{\mathbf{Q}^{\mathrm{v}}}$$

$$\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = \nabla \cdot \{\mu \nabla \mathbf{v}\} - \nabla p + \mathbf{Q}^{\mathbf{v}}$$



6. Conservation of Linear Momentum General form – for Newtonian Fluids

 $\square$  For incompressible flows:  $abla \cdot \mathbf{v} = \mathbf{0}$ 

$$\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = -\nabla p + \nabla \cdot \left\{ \mu \left[ \nabla \mathbf{v} + (\nabla \mathbf{v})^{\mathrm{T}} \right] \right\} + \mathbf{f}_{b}$$

 Divergence of the stress tensor for the incompressible flows:

$$\mu \frac{\partial}{\partial x} \left[ 2 \frac{\partial u}{\partial x} \right] + \mu \frac{\partial}{\partial y} \left[ \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \mu \frac{\partial}{\partial z} \left[ \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \right]$$

$$= \mu \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 v}{\partial yx} + \frac{\partial^2 u}{\partial z^2} + \frac{\partial^2 w}{\partial zx} \right]$$

$$= \mu \left[ \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial yx} + \frac{\partial^2 w}{\partial zx} \right]$$

$$= \mu \left[ \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right]$$



6. Conservation of Linear Momentum General form – for Newtonian Fluids

□ And Finally:

 $\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = -\nabla p + \mu \nabla^2 \mathbf{v} + \mathbf{f}_b$ 



- □ First law of Thermodynamics
  - □ Total Energy *E*
- □ Different Terms of work and heat

$$E = m \left( \hat{u} + \frac{1}{2} \mathbf{v} \cdot \mathbf{v} \right)$$
$$\left( \frac{dE}{dt} \right)_{MV} = \dot{Q} - \dot{W}$$

$$\left(\frac{dE}{dt}\right)_{MV} = \dot{Q}_V + \dot{Q}_S - \dot{W}_b - \dot{W}_S$$



$$\dot{Q}_V = \int\limits_V \dot{q}_V dV \quad \dot{Q}_S = -\int\limits_S \dot{q}_s \cdot \mathbf{n} \, dS = -\int\limits_V \nabla \cdot \dot{q}_s dV$$

Heat Rates

□ Work Rates

$$\dot{W}_b = -\int\limits_V (\mathbf{f}_b \cdot \mathbf{v}) dV$$
  $\dot{W}_S = -\int\limits_S (\mathbf{f}_S \cdot \mathbf{v}) dS$ 

$$\dot{W}_{S} = -\int_{S} [\Sigma \cdot \mathbf{v}] \cdot \mathbf{n} \, dS = -\int_{V} \nabla \cdot [\Sigma \cdot \mathbf{v}] dV = -\int_{V} \nabla \cdot [(-p\mathbf{I} + \mathbf{\tau}) \cdot \mathbf{v}] dV$$

$$\dot{W}_S = -\int\limits_V (-
abla \cdot [p\mathbf{v}] + 
abla \cdot [\mathbf{\tau} \cdot \mathbf{v}]) dV$$



□ Applying RTT

$$B = E \Rightarrow b = \frac{dE}{dm} = \hat{u} + \frac{1}{2}\mathbf{v}\cdot\mathbf{v} = e$$

$$\frac{dE}{dt}\Big)_{MV} = \int_{V} \left[\frac{\partial}{\partial t}(\rho e) + \nabla \cdot [\rho \mathbf{v}e]\right] dV$$
$$= -\int_{V} \nabla \cdot \dot{q}_{s} dV + \int_{V} (-\nabla \cdot [p\mathbf{v}] + \nabla \cdot [\mathbf{\tau} \cdot \mathbf{v}]) dV + \int_{V} (\mathbf{f}_{b} \cdot \mathbf{v}) dV + \int_{V} \dot{q}_{V} dV$$



□ Collecting Terms to one side

$$\int_{V} \left[ \frac{\partial}{\partial t} (\rho e) + \nabla \cdot [\rho \mathbf{v} e] + \nabla \cdot \dot{q}_{s} + \nabla \cdot [p \mathbf{v}] - \nabla \cdot [\mathbf{\tau} \cdot \mathbf{v}] - \mathbf{f}_{b} \cdot \mathbf{v} - \dot{q}_{V} \right] dV = 0$$

□ For any CV :

$$\frac{\partial}{\partial t}(\rho e) + \nabla \cdot [\rho \mathbf{v} e] = -\nabla \cdot \dot{q}_s - \nabla \cdot [p\mathbf{v}] + \nabla \cdot [\mathbf{\tau} \cdot \mathbf{v}] + \mathbf{f}_b \cdot \mathbf{v} + \dot{q}_V$$



7. Conservation of Energy – in terms of specific Internal Energy

□ From the conservation of momentum eq. we have

 $\frac{\partial}{\partial t}[\rho \mathbf{v}] + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\} = \mathbf{f}$ 

- □ Its dot product in velocity vector would result in
- After some manipulations:

$$\left[\frac{\partial}{\partial t}(\rho \mathbf{v}) + \nabla \cdot \{\rho \mathbf{v} \mathbf{v}\}\right] \cdot \mathbf{v} = \mathbf{f} \cdot \mathbf{v}$$

$$\frac{\partial}{\partial t}(\rho \mathbf{v} \cdot \mathbf{v}) - \rho \mathbf{v} \cdot \frac{\partial \mathbf{v}}{\partial t} + \nabla \cdot [\rho(\mathbf{v} \cdot \mathbf{v})\mathbf{v}] - \rho \mathbf{v} \cdot [(\mathbf{v} \cdot \nabla)\mathbf{v}] = \mathbf{f} \cdot \mathbf{v}$$

Rearranging and Collecting Terms

$$\frac{\partial}{\partial t}(\rho \mathbf{v} \cdot \mathbf{v}) + \nabla \cdot [\rho(\mathbf{v} \cdot \mathbf{v})\mathbf{v}] - \mathbf{v} \cdot \underbrace{\rho\left[\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla)\mathbf{v}\right]}_{=\mathbf{f}} = \mathbf{f} \cdot \mathbf{v}$$



7. Conservation of Energy – in terms of specific Internal Energy

Image: Using the general form of the conservation of linear<br/>momentum, we would get $\partial (1)$ 

□ It can be rewritten as

$$\frac{\partial}{\partial t} \left( \rho \frac{1}{2} \mathbf{v} \cdot \mathbf{v} \right) + \nabla \cdot \left[ \rho \left( \frac{1}{2} \mathbf{v} \cdot \mathbf{v} \right) \mathbf{v} \right] = -\mathbf{v} \cdot \nabla p + \mathbf{v} \cdot \left[ \nabla \cdot \mathbf{\tau} \right] + \mathbf{f}_b \cdot \mathbf{v}$$

$$\frac{\partial}{\partial t} \left( \rho \frac{1}{2} \mathbf{v} \cdot \mathbf{v} \right) + \nabla \cdot \left[ \rho \left( \frac{1}{2} \mathbf{v} \cdot \mathbf{v} \right) \mathbf{v} \right]$$
  
=  $-\nabla \cdot [p\mathbf{v}] + p\nabla \cdot \mathbf{v} + \nabla \cdot [\mathbf{\tau} \cdot \mathbf{v}] - (\mathbf{\tau} : \nabla \mathbf{v}) + \mathbf{f}_b \cdot \mathbf{v}$ 

□ Thus, using the definition of specific internal energy

$$\frac{\partial}{\partial t}(\rho \hat{u}) + \nabla \cdot [\rho \mathbf{v} \hat{u}] = -\nabla \cdot \dot{q}_s - p\nabla \cdot \mathbf{v} + (\mathbf{\tau} : \nabla \mathbf{v}) + \dot{q}_V$$



- 7. Conservation of Energy in terms of specific Enthalpy
- □ Its definition

$$\hat{u} = \hat{h} - \frac{p}{\rho}$$

□ Thus, after some algebraic manipulations:

$$\frac{\partial}{\partial t} \left( \rho \hat{h} \right) + \nabla \cdot \left[ \rho \mathbf{v} \hat{h} \right] = -\nabla \cdot \dot{q}_s + \frac{Dp}{Dt} + (\mathbf{\tau} : \nabla \mathbf{v}) + \dot{q}_V$$



7. Conservation of Energy – in terms of specific total Enthalpy

□ Its definition

$$e = \hat{u} + \frac{1}{2}\mathbf{v} \cdot \mathbf{v} = \hat{h} - \frac{p}{\rho} + \frac{1}{2}\mathbf{v} \cdot \mathbf{v} = \hat{h}_0 - \frac{p}{\rho}$$

□ Thus, after some algebraic manipulations:

$$\frac{\partial}{\partial t} \left( \rho \hat{h}_0 \right) + \nabla \cdot \left[ \rho \mathbf{v} \hat{h}_0 \right] = -\nabla \cdot \dot{q}_s + \frac{\partial p}{\partial t} + \nabla \cdot \left[ \mathbf{\tau} \cdot \mathbf{v} \right] + \mathbf{f}_b \cdot \mathbf{v} + \dot{q}_V$$



- 7. Conservation of Energy in terms of Temperature
- □ Based on thermodynamic relations

$$d\hat{h} = c_p dT + \left[\hat{V} - T\left(\frac{\partial\hat{V}}{\partial T}\right)_p\right]dp$$

□ The substantial derivative of specific enthalpy is

$$\frac{\partial}{\partial t}(\rho \hat{h}) + \nabla \cdot \left[\rho \mathbf{v} \hat{h}\right] = \rho \frac{D \hat{h}}{D t} = \rho c_p \frac{DT}{D t} + \rho \left[\hat{V} - T \left(\frac{\partial \hat{V}}{\partial T}\right)_p\right] \frac{DP}{D t}$$
$$= \rho c_p \frac{DT}{D t} + \rho \left[\frac{1}{\rho} - T \left(\frac{\partial (1/\rho)}{\partial T}\right)_p\right] \frac{DP}{D t}$$
$$= \rho c_p \frac{DT}{D t} + \left[1 + \left(\frac{\partial (L n \rho)}{\partial (L n T)}\right)_p\right] \frac{DP}{D t}$$



7. Conservation of Energy – in terms of Temperature

Using the eq. for conservation of energy in terms of specific enthalpy, we would get

$$\rho c_p \frac{DT}{Dt} = -\nabla \cdot \dot{q}_s - \left(\frac{\partial (Ln\rho)}{\partial (LnT)}\right)_p \frac{Dp}{Dt} + (\mathbf{\tau} : \nabla \mathbf{v}) + \dot{q}_V$$

□ By expanding the substantial derivative

$$c_p \left[ \frac{\partial}{\partial t} (\rho T) + \nabla \cdot [\rho \mathbf{v} T] \right] = -\nabla \cdot \dot{q}_s - \left( \frac{\partial (Ln\rho)}{\partial (LnT)} \right)_p \frac{Dp}{Dt} + (\mathbf{\tau} : \nabla \mathbf{v}) + \dot{q}_V$$



- 7. Conservation of Energy in terms of Temperature
- $\Box$  The Heat Flux term,  $\dot{q}s$
- □ Thus,

$$\dot{q}_s = -[k 
abla T]$$

$$c_p \left[ \frac{\partial}{\partial t} (\rho T) + \nabla \cdot [\rho \mathbf{v} T] \right] = \nabla \cdot [k \nabla T] - \left( \frac{\partial (Ln\rho)}{\partial (LnT)} \right)_p \frac{Dp}{Dt} + (\mathbf{\tau} : \nabla \mathbf{v}) + \dot{q}_V$$



7. Conservation of Energy – in terms of Temperature

 $\Box$   $\;$  The expression for  $(\tau: \nabla v)$  , in Cartesian 3D is given by

$$(\tau:\nabla\mathbf{v}) = \lambda \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)^2 + \mu \left(\frac{2\left(\frac{\partial u}{\partial x}\right)^2 + 2\left(\frac{\partial v}{\partial y}\right)^2 + 2\left(\frac{\partial w}{\partial z}\right)^2}{+\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y}\right)^2\right)$$

 $\Box$   $\,$  We can define  $\,\Psi\,$  and  $\,\Phi\,$  as

$$\Psi = \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right)^2$$

$$\Phi = 2\left[\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2 + \left(\frac{\partial w}{\partial z}\right)^2\right] + \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y}\right)^2$$



7. Conservation of Energy – in terms of Temperature

□ Thus, we get:

□ For later reference,

$$c_{p}\left[\frac{\partial}{\partial t}(\rho T) + \nabla \cdot [\rho \mathbf{v}T]\right] = \nabla \cdot [k\nabla T] - \left(\frac{\partial(Ln\,\rho)}{\partial(Ln\,T)}\right)_{p}\frac{Dp}{Dt} + \lambda\Psi + \mu\Phi + \dot{q}_{V}$$
$$\frac{\partial}{\partial t}(\rho c_{p}T) + \nabla \cdot [\rho c_{p}\mathbf{v}T] = \nabla \cdot [k\nabla T]$$
$$+ \rho T\frac{Dc_{p}}{Dt} - \left(\frac{\partial(Ln\,\rho)}{\partial(Ln\,T)}\right)_{p}\frac{Dp}{Dt} + \lambda\Psi + \mu\Phi + \dot{q}_{V}$$
$$\underbrace{Q^{T}}$$

$$\frac{\partial}{\partial t} \left( \rho c_p T \right) + \nabla \cdot \left[ \rho c_p \mathbf{v} T \right] = \nabla \cdot \left[ k \nabla T \right] + Q^T$$



7. Conservation of Energy – in terms of Temperature

$$\frac{\partial}{\partial t} \left( \rho c_p T \right) + \nabla \cdot \left[ \rho c_p \mathbf{v} T \right] = \nabla \cdot \left[ k \nabla T \right] + Q^T$$

□ Special Cases,

 $\Box$  The Dissipation term  $\Phi$  , has negligible values except for large velocity gradients at supersonic speeds

For incompressible fluids, the continuity eq. implies that  $\Psi = 0$ thus,  $(\partial (Ln\rho)/\partial (LnT)) = 0$ .

and for this case,

$$\frac{\partial}{\partial t} \left( \rho c_p T \right) + \nabla \cdot \left[ \rho c_p \mathbf{v} T \right] = \nabla \cdot \left[ k \nabla T \right] + \underbrace{\dot{q}_V + \rho T \frac{D c_p}{D t}}_{Q^T}$$



7. Conservation of Energy – in terms of Temperature

$$\frac{\partial}{\partial t} \left( \rho c_p T \right) + \nabla \cdot \left[ \rho c_p \mathbf{v} T \right] = \nabla \cdot \left[ k \nabla T \right] + Q^T$$

□ Special Cases,

 For solids, density is constant, the velocity is zero, k would be considered constant too, thus

$$\rho c_p \frac{\partial T}{\partial t} = k \nabla^2 T + \dot{q}_V$$

□ For the ideal gases,  $(\partial(Ln\rho)/\partial(LnT)) = -1$ thus the eq. reduces to

$$c_p \left[ \frac{\partial}{\partial t} (\rho T) + \nabla \cdot [\rho \mathbf{v} T] \right] = \nabla \cdot [k \nabla T] + \frac{Dp}{Dt} + \lambda \Psi + \mu \Phi + \dot{q}_V$$



 $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$ 

□ Governing eqs. In 3D Cartesian System

$$\frac{\partial}{\partial t}(\rho u) + \frac{\partial}{\partial x}(\rho u u) + \frac{\partial}{\partial y}(\rho v u) + \frac{\partial}{\partial z}(\rho w u) = -\frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}\right)$$
$$\frac{\partial}{\partial t}(\rho v) + \frac{\partial}{\partial x}(\rho u v) + \frac{\partial}{\partial y}(\rho v v) + \frac{\partial}{\partial z}(\rho w v) = -\frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2}\right) - \rho g$$
$$\frac{\partial}{\partial t}(\rho w) + \frac{\partial}{\partial x}(\rho u w) + \frac{\partial}{\partial y}(\rho v w) + \frac{\partial}{\partial z}(\rho w w) = -\frac{\partial p}{\partial z} + \mu \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2}\right)$$
$$c_p \left[\frac{\partial}{\partial t}(\rho T) + \frac{\partial}{\partial x}(\rho u T) + \frac{\partial}{\partial y}(\rho v T) + \frac{\partial}{\partial z}(\rho w T)\right] = k \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2}\right)$$



Boussinesq Approximation

$$\frac{\partial}{\partial t}(\rho v) + \frac{\partial}{\partial x}(\rho u v) + \frac{\partial}{\partial y}(\rho v v) + \frac{\partial}{\partial z}(\rho w v) = -\frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2}\right) - \rho g$$

Density using Taylor Expansion

 $ho = 
ho |_{T=T_{\infty}} + rac{d
ho}{dT} \Big|_{T=T_{\infty}} (T-T_{\infty})$ 

□ Volume Expansion coeff.

$$\beta = -\frac{1}{\rho} \left( \frac{\partial \rho}{\partial T} \right)_p$$

- Thus, the density becomes
- And Finally

$$\rho = \rho_{\infty}[1 - \beta(T - T_{\infty})]$$

$$\frac{\partial}{\partial t}(\rho v) + \frac{\partial}{\partial x}(\rho u v) + \frac{\partial}{\partial y}(\rho v v) + \frac{\partial}{\partial z}(\rho w v)$$
$$= -\frac{\partial}{\partial y}(\rho + \rho g y) + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2}\right) + \rho g \beta (T - T_{\infty})$$



□ Non-dimensional form of variables

$$\hat{x} = \frac{x}{L}, \hat{y} = \frac{y}{L}, \hat{z} = \frac{z}{L}$$
$$\hat{u} = \frac{u}{\mu/(\rho L)}, \hat{v} = \frac{v}{\mu/(\rho L)}, \hat{w} = \frac{w}{\mu/(\rho L)}$$
$$\hat{t} = \frac{t}{\rho L^2/\mu}$$
$$\hat{p} = \frac{p + \rho g y}{\mu^2/(\rho L^2)}$$
$$\hat{T} = \frac{T - T_{\infty}}{T_{\max} - T_{\infty}}$$



□ Non-dimensionalization of some of the terms in governing eqs.

$$\begin{aligned} \frac{\partial u}{\partial x} &= \frac{\partial [\mu \hat{u}/(\rho L)]}{\partial (L \hat{x})} = \frac{\mu/(\rho L)}{L} \frac{\partial \hat{u}}{\partial \hat{x}} = \frac{\mu}{\rho L^2} \frac{\partial \hat{u}}{\partial \hat{x}} \\ \frac{\partial}{\partial t}(\rho u) &= \frac{\partial (\mu \hat{u}/L)}{\partial (\rho L^2 \hat{t}/\mu)} = \frac{\mu/L}{\rho L^2/\mu} \frac{\partial \hat{u}}{\partial \hat{t}} = \frac{\mu^2}{\rho L^3} \frac{\partial \hat{u}}{\partial \hat{t}} \\ \frac{\partial}{\partial t}(\rho u u) &= \frac{\partial [\mu^2/(\rho L^2) \hat{u} \hat{u}]}{\partial (L \hat{x})} = \frac{\mu^2/(\rho L^2)}{L} \frac{\partial}{\partial \hat{x}} (\hat{u} \hat{u}) = \frac{\mu^2}{\rho L^3} \frac{\partial}{\partial \hat{x}} (\hat{u} \hat{u}) \\ \hat{p} &= \frac{p + \rho g y}{\mu^2/(\rho L^2)} \Rightarrow \frac{\partial \hat{p}}{\partial \hat{x}} = \frac{\partial \{(p + \rho g y)/[\mu^2/(\rho L^2)]\}}{\partial (x/L)} \\ &= \frac{\rho L^3}{\mu^2} \frac{\partial p}{\partial x} \Rightarrow \frac{\partial p}{\partial x} = \frac{\mu^2}{\rho L^3} \frac{\partial \hat{p}}{\partial \hat{x}} \end{aligned}$$

41



□ Non-dimensionalization of some of the terms in governing eqs.

$$\mu \frac{\partial^2 u}{\partial x^2} = \mu \frac{\partial^2 [\mu \hat{u} / (\rho L)]}{\partial (L\hat{x})^2} = \mu \frac{\mu / (\rho L)}{L^2} \frac{\partial^2 \hat{u}}{\partial \hat{x}^2} = \frac{\mu^2}{\rho L^3} \frac{\partial^2 \hat{u}}{\partial \hat{x}^2}$$

$$\rho g \beta (T - T_\infty) = \rho g \beta (T_{\max} - T_\infty) \hat{T} = \rho g \beta (\Delta T) \hat{T}$$

$$\frac{\partial}{\partial t} (\rho T) = \frac{\partial [\rho (T_\infty + \Delta T \hat{T})]}{\partial (\rho L^2 \hat{t} / \mu)} = \frac{\mu \Delta T}{L^2} \frac{\partial \hat{T}}{\partial \hat{t}}$$

$$\frac{\partial}{\partial x} (\rho u T) = \frac{\partial (\mu \hat{u} (T_\infty + \Delta T \hat{T}) / L)}{\partial (L\hat{x})} = \frac{\mu T_\infty}{L^2} \frac{\partial \hat{u}}{\partial \hat{x}} + \frac{\mu \Delta T}{L^2} \frac{\partial}{\partial \hat{x}} (\hat{u} \hat{T})$$

$$k \frac{\partial^2 T}{\partial x^2} = k \frac{\partial^2 (T_\infty + \Delta T \hat{T})}{\partial (L\hat{x})^2} = \frac{k \Delta T}{L^2} \frac{\partial^2 \hat{T}}{\partial \hat{x}^2}$$



 $\frac{\partial \hat{u}}{\partial \hat{x}} + \frac{\partial \hat{v}}{\partial \hat{y}} + \frac{\partial \hat{w}}{\partial \hat{z}} = 0$ 

□ Non-dimensionalized Governing Eqs.

$$Gr = \frac{g\beta\Delta TL^3}{v^2}$$
$$v = \frac{\mu c_p}{k}$$

$$\frac{\partial \hat{u}}{\partial \hat{t}} + \frac{\partial}{\partial \hat{x}} (\hat{u}\hat{u}) + \frac{\partial}{\partial \hat{y}} (\hat{v}\hat{u}) + \frac{\partial}{\partial \hat{z}} (\hat{w}\hat{u}) = -\frac{\partial \hat{p}}{\partial \hat{x}} + \left(\frac{\partial^2 \hat{u}}{\partial \hat{x}^2} + \frac{\partial^2 \hat{u}}{\partial \hat{y}^2} + \frac{\partial^2 \hat{u}}{\partial \hat{z}^2}\right)$$

$$\frac{\partial \hat{v}}{\partial \hat{t}} + \frac{\partial}{\partial \hat{x}} (\hat{u}\hat{v}) + \frac{\partial}{\partial \hat{y}} (\hat{v}\hat{v}) + \frac{\partial}{\partial \hat{z}} (\hat{w}\hat{v}) = -\frac{\partial \hat{p}}{\partial \hat{y}} + \left(\frac{\partial^2 \hat{v}}{\partial \hat{x}^2} + \frac{\partial^2 \hat{v}}{\partial \hat{y}^2} + \frac{\partial^2 \hat{v}}{\partial \hat{z}^2}\right) + Gr\hat{T}$$

$$\frac{\partial \hat{w}}{\partial \hat{t}} + \frac{\partial}{\partial \hat{x}} (\hat{u}\hat{w}) + \frac{\partial}{\partial \hat{y}} (\hat{v}\hat{w}) + \frac{\partial}{\partial \hat{z}} (\hat{w}\hat{w}) = -\frac{\partial \hat{p}}{\partial \hat{z}} + \left(\frac{\partial^2 \hat{w}}{\partial \hat{x}^2} + \frac{\partial^2 \hat{w}}{\partial \hat{y}^2} + \frac{\partial^2 \hat{w}}{\partial \hat{z}^2}\right)$$

$$\frac{\partial \hat{T}}{\partial \hat{t}} + \frac{\partial}{\partial \hat{x}} (\hat{u}\hat{T}) + \frac{\partial}{\partial \hat{y}} (\hat{v}\hat{T}) + \frac{\partial}{\partial \hat{z}} (\hat{w}\hat{T}) = \frac{1}{Pr} \left(\frac{\partial^2 \hat{T}}{\partial \hat{x}^2} + \frac{\partial^2 \hat{T}}{\partial \hat{y}^2} + \frac{\partial^2 \hat{T}}{\partial \hat{z}^2}\right)$$



#### 9. Dimensionless Numbers - Re

#### Definition

 $Re = rac{
ho UL}{\mu}$ 

Turbulent flow region A measure of relative Transition region importance of advection  $Re > 5x10^5$ Laminar flow region (inertia) to diffusion Viscous sublayer (viscous) momentum  $Re < 5x10^5$ fluxes Flow -Re = 10Re = 100Re = 1000Re = 4000



9. Dimensionless Numbers - Gr

Definition

 $Gr = \frac{g\beta\Delta TL^3}{v^2}$ 

- Represents the ratio of buoyant to viscous forces
  It plays the role of Re in Natural Convection





9. Dimensionless Numbers - Pr

Definition

 $Pr = \frac{\mu c_p}{k} = \frac{\mu/\rho}{k/\rho c_p} = \frac{\nu}{\alpha}$ 

Represents the ratio of momentum diffusivity to thermal diffusivity
 Also represents the ratio of hydrodynamic boundary layer to thermal

boundary layer





#### 9. Dimensionless Numbers - Pr

Definition

$$Pr = \frac{\mu c_p}{k} = \frac{\mu/\rho}{k/\rho c_p} = \frac{\nu}{\alpha}$$



Pr > 1



9. Dimensionless Numbers - Pe

Definition

 $Pe = \frac{\rho ULc_p}{k} = \frac{UL}{\alpha} = Re^*Pr$ 

 Ratio of the advective transport rate of a physical quantity to its diffusive transport rate

 $Pe = \frac{UL}{D} = Re^*Sc$ 





#### 9. Dimensionless Numbers - Sc

- Definition
- □ Like Pr but for mass transfer
- Represents the ratio of the momentum diffusivity to mass diffusivity
- Also relates the thickness of hydrodynamic boundary layer to mass transfer boundary layer



 $Sc = \frac{v}{D}$ 



9. Dimensionless Numbers - Nu

Definition

 Not brought up in non-dimensionalization of conservation equations but widely used in information of convective transport  $Nu = \frac{hL}{k}$ 



9. Dimensionless Numbers - Mach

Definition

 $M = \frac{|\mathbf{v}|}{a}$ 

 Ratio of speed of an object moving through a fluid and the local speed of sound
 General relation for local speed of sound

 $a = \sqrt{\gamma \left(\frac{\partial p}{\partial \rho}\right)_T}$ 

- □ For an ideal gas, it reduces to
- □ If M<0.2 the flow can be treated as incompressible</li>
   □ Suubsonic Sonic Supersonic Hypersonic

 $a = \sqrt{\gamma RT}$ 



9. Dimensionless Numbers - Ec

Definition

 $Ec = \frac{\mathbf{v} \cdot \mathbf{v}}{c_p \Delta T}$ 

- Image: Relates the kinetic energy of the flow to its enthalpy
- □ It appears as a factor multiplying the viscous dissipation



#### 9. Dimensionless Numbers - Fr

Definition

 $Fr = \frac{U}{\sqrt{gL}}$ 

 A measure of the resistance of partially immersed objects moving through fluids





9. Dimensionless Numbers - We

Definition

 $We = \frac{\rho U^2 L}{2}$ 

- □ Represents the ratio of inertia to surface tension forces
- It is helpful in analyzing multiphase flow involving interfaces between two different fluids, with curved surfaces such as droplets and bubbles



#### Problem 01

Let  $\mathbf{v}_1, \mathbf{v}_2$  and  $\mathbf{v}_3$  be three vectors given by

$$\mathbf{v}_1 = \begin{bmatrix} 1\\2\\-5 \end{bmatrix} \quad \mathbf{v}_2 = \begin{bmatrix} -1\\-1\\10 \end{bmatrix} \quad \mathbf{v}_3 = \begin{bmatrix} 8\\-5\\-2 \end{bmatrix}$$

#### Find:

a.  $\mathbf{v}_1 + \mathbf{v}_2$ ,  $\mathbf{v}_1 + 2\mathbf{v}_2$ ,  $3\mathbf{v}_2 - 4\mathbf{v}_3$ b.  $|\mathbf{v}_1|$ ,  $|\mathbf{v}_2|$ ,  $|\mathbf{v}_3|$ c.  $\mathbf{v}_1 \cdot \mathbf{v}_2$ ,  $\mathbf{v}_3 \times \mathbf{v}_2$ ,  $\mathbf{v}_2 \cdot (\mathbf{v}_1 \times \mathbf{v}_3)$ d. A unit vector in the direction of  $(\mathbf{v}_1 + \mathbf{v}_2 + \mathbf{v}_3)$ 



Problem 02

Let  $\mathbf{i}$ ,  $\mathbf{j}$  and  $\mathbf{k}$  be unit vectors in the *x*, *y*, and *z* direction, respectively, and let  $\mathbf{v}$  be any vector, which in a Cartesian coordinate system is given by

 $\mathbf{v} = u\mathbf{i} + v\mathbf{j} + w\mathbf{k}$ 

Prove that

$$\mathbf{v} = C[\mathbf{i} \times (\mathbf{v} \times \mathbf{i}) + \mathbf{j} \times (\mathbf{v} \times \mathbf{j}) + \mathbf{k} \times (\mathbf{v} \times \mathbf{k})]$$

where C is a constant to be determined.



Problem 03

#### Find $\nabla s$ if s is the scalar function given by

a. 
$$s = y^2 e^{2x-3z}$$
  
b.  $s = Ln(x + y^2 + z^3)$   
c.  $s = tan^{-1}\left(\frac{x}{yz}\right)$ 



Problem 04

Find the Laplacian of the scalar s ( $\nabla^2 s$ ) for the cases when s is given by:

a. 
$$s = x^{3} + z^{2}e^{2y-3x}$$
  
b.  $s = z + Ln(x + y)$   
c.  $s = sin^{-1}(x + y + z)$ 



Problem 05

Use the divergence theorem to evaluate the integral  $\iint_{\partial F} (6x\mathbf{i} + 4y\mathbf{j}) \cdot d\mathbf{F}$  where the surface is a sphere defined as  $\partial F \rightarrow x^2 + y^2 + z^2 = 10$ .





Problem 06

#### Show that for an incompressible flow of constant viscosity the following holds:

$$\nabla \cdot \left\{ \mu \left[ \nabla \mathbf{v} + (\nabla \mathbf{v})^{\mathrm{T}} \right] \right\} = \mu \nabla^{2} \mathbf{v}$$



Problem 07

A steady incompressible flow field is defined by the following velocity vector:

$$\mathbf{v} = (x+y)\mathbf{i} + (y+z)\mathbf{j} + 2(x-z)\mathbf{k}$$

- (a) Verify that it satisfies the continuity equation.
- (b) Assuming constant viscosity  $\mu$ , calculate the viscous stress tensor  $\tau$ .
- (c) Denoting the fluid density by  $\rho$  and neglecting body forces, develop an equation for the pressure gradient.



#### Problem 08

Starting from the incompressible version of the Navier-Stokes equations derive simplified equations based on the following assumptions:

(a) Viscous effects are much more significant than any effects of fluid acceleration, i.e.,

$$\frac{\partial}{\partial t}(\mathbf{v}) + \nabla \cdot [\mathbf{v}\mathbf{v}] \ll \nabla \cdot [\mu \nabla \mathbf{v}]$$

which corresponds to  $Re = \rho UL/\mu \ll 1$  (Stokes Equations).

(b) Inertial effects dominate and viscous effects are considered to be negligible throughout the flow domain, i.e.,

$$\frac{\partial}{\partial t}(\mathbf{v}) + \nabla \cdot [\mathbf{v}\mathbf{v}] \gg \nabla \cdot [\mu \nabla \mathbf{v}]$$

which corresponds to  $Re = \rho UL/\mu \gg 1$  (Euler equations).

(c) Derive the Bernoulli equation from momentum conservation with the following hypothesis: one dimensional steady state conditions of a frictionless fluid  $\mu = 0$ .



# Thanks for your time and attention